## Analytical inversion of general tridiagonal matrices

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# Analytical inversion of general tridiagonal matrices 

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#### Abstract

In this paper we give a complete analysis for general tridiagonal matrix inversion for both non-block and block cases, and provide some very simple analytical formulae which immediately lead to closed forms for some special cases such as symmetric or Toeplitz tridiagonal matrices.


## 1. Introduction

The need to find the inverse of tridiagonal matrices arises in many scientific and engineering applications. This problem has been investigated for a few decades with an attempt to find a simple and explicit analytic expression for the inverse. However, most of their efforts ended up with formulae for some special cases where the tridiagonal matrix is symmetric Toeplitz, see [1, 7] for example, or some fairly sophisticated formulae that rely on some strict requirements such as that all the entries of the lower/upper diagonals must not be zero, see $[5,3,6]$ for example. For a review of the symmetric tridiagonal matrix inverse please refer to [4]. In this paper, we relate general tridiagonal matrix inversion to second-order linear recurrences and provide a set of very simple analytical formulae for both scalar and block cases. These formulae can immediately lead to closed forms for certain tridiagonal matrices such as general (block) Toeplitz tridiagonal matrices. The properties of the inverse are also discussed. To our knowledge, this is the first complete analysis for the general tridiagonal matrix inversion problem.

The paper is organized as follows. In section 2, we give an analytical formula for a general scalar tridiagonal matrix inversion and discuss some properties of the inverse. In section 3, the result is applied to the case of a general Toeplitz tridiagonal matrix and a closed-form expression for the inverse is obtained. In section 4, a formula for a general block tridiagonal matrix is presented. An extension to the block Toeplitz case is given in section 5. Part of the proof of the results have appeared in [2] and are included in the appendix.

[^0]
## 2. Non-block case

We consider the inverse of a tridiagonal matrix

$$
A=\left[\begin{array}{ccccccc}
b_{1} & c_{1} & & & & & \\
a_{2} & b_{2} & c_{2} & & & & \\
& \ddots & \ddots & \ddots & & & \\
& & a_{j} & b_{j} & c_{j} & & \\
& & & \ddots & \ddots & \ddots & \\
& & & & a_{n-1} & b_{n-1} & c_{n-1} \\
& & & & & a_{n} & b_{n}
\end{array}\right]
$$

### 2.1. Main results

Theorem 2.1. Define the second-order linear recurrences

$$
\begin{equation*}
z_{i}=b_{i} z_{i-1}-a_{i} c_{i-1} z_{i-2} \quad i=2,3, \ldots, n \tag{1}
\end{equation*}
$$

where $z_{0}=1, z_{1}=b_{1}$, and

$$
\begin{equation*}
y_{j}=b_{j} y_{j+1}-a_{j+1} c_{j} y_{j+2} \quad j=n-1, n-2, \ldots, 1 \tag{2}
\end{equation*}
$$

where $y_{n+1}=1, y_{n}=b_{n}$. The inverse matrix $A^{-1}=\left\{\phi_{i, j}\right\}(1 \leqslant i, j \leqslant n)$ can be expressed as

$$
\begin{equation*}
\phi_{j, j}=\frac{1}{b_{j}-a_{j} c_{j-1} \frac{z_{j-2}}{z_{j-1}}-a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}} \tag{3}
\end{equation*}
$$

where $j=1,2, \ldots, n, a_{1}=0, c_{n}=0$ and

$$
\phi_{i, j}= \begin{cases}-c_{i} \frac{z_{i-1}}{z_{i}} \phi_{i+1, j} & i<j  \tag{4}\\ -a_{i} \frac{y_{i+1}}{y_{i}} \phi_{i-1, j} & i>j\end{cases}
$$

Proof. See appendix A.

Corollary 2.1. The inverse matrix $A^{-1}=\left\{\phi_{i, j}\right\}$ can be expressed as

$$
\phi_{j, j}=\frac{1}{b_{j}-a_{j} c_{j-1} \frac{z_{j-2}}{z_{j-1}}-a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}}
$$

where $j=1,2, \ldots, n, a_{1}=0, c_{n}=0$ and

$$
\phi_{i, j}= \begin{cases}(-1)^{j-i}\left(\prod_{k=1}^{j-i} c_{j-k}\right) \frac{z_{i-1}}{z_{j-1}} \phi_{j, j} & i<j  \tag{5}\\ (-1)^{i-j}\left(\prod_{k=1}^{i-j} a_{j+k}\right) \frac{y_{i+1}}{y_{j+1}} \phi_{j, j} & i>j\end{cases}
$$

Theorem 2.2. The inverse of the tridiagonal matrix $A$ can be computed in $n^{2}+7 n-7$ arithmetic operations.

Proof. See appendix B.

### 2.2. Properties of the inverse matrix

From theorem 2.1, we can easily obtain the following results.
Theorem 2.3. If any element of the lower-diagonal of $A$ is zero, i.e. if $a_{k}=0(2 \leqslant k \leqslant n)$, then

$$
\begin{equation*}
\phi_{i, j}=0 \quad \text { where } i=k \sim n, j=1 \sim k-1 \tag{6}
\end{equation*}
$$

If any element of the super-diagonal of $A$ is zero, i.e. if $c_{k}=0(1 \leqslant k \leqslant n-1)$, then

$$
\begin{equation*}
\phi_{i, j}=0 \quad \text { where } i=1 \sim k, j=k+1 \sim n \tag{7}
\end{equation*}
$$

Lemma 2.1. If $A$ is strictly diagonally dominant, i.e. $\left|b_{i}\right|>\left|a_{i}\right|+\left|c_{i}\right|$ for all $1 \leqslant i \leqslant n$, then

$$
\begin{equation*}
\left|z_{i}\right|>\left|c_{i} z_{i-1}\right| \quad i=1, \ldots, n \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|y_{j}\right|>\left|a_{j} y_{j+1}\right| \quad j=n, \ldots, 1 \tag{9}
\end{equation*}
$$

Proof. We use induction on $i$.
When $i=1$, ( 8 ) holds since

$$
\left|z_{1}\right|=\left|b_{1}\right|>\left|c_{1} z_{0}\right|=\left|c_{1}\right|
$$

Suppose (8) holds for all $1 \leqslant i \leqslant k-1<n-1$, then we have

$$
\begin{aligned}
\left|z_{k}\right| & =\left|b_{k} z_{k-1}-a_{k} c_{k-1} z_{k-2}\right| \\
& \geqslant\left|b_{k}\right|\left|z_{k-1}\right|-\left|a_{k}\right|\left|c_{k-1} z_{k-2}\right| \\
& \geqslant\left|b_{k}\right|\left|z_{k-1}\right|-\left|a_{k}\right|\left|z_{k-1}\right| \\
& >\left|c_{k}\right|\left|z_{k-1}\right| .
\end{aligned}
$$

Thus (8) holds for all $1 \leqslant i \leqslant n$. Similarly, we have $\left|y_{j}\right|>\left|a_{j} y_{j+1}\right|$ for all $1 \leqslant j \leqslant n$.

Theorem 2.4. If $A$ is strictly diagonally dominant, i.e. $\left|b_{i}\right|>\left|a_{i}\right|+\left|c_{i}\right|$ for all $1 \leqslant i \leqslant n$, then theorem 2.1 will not break down.

Proof. All we need to do is to show $z_{i} \neq 0, y_{i} \neq 0$ and $b_{j}-a_{j} c_{j-1} \frac{z_{j-2}}{z_{j-1}}-a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}} \neq 0$ for all $1 \leqslant i \leqslant n$.

From lemma 2.1, since $\left|z_{1}\right|=\left|b_{1}\right| \neq 0$, it is obvious that $\left|z_{i}\right|>0$ for all $1 \leqslant i \leqslant n$. Similarly, since $\left|y_{n}\right|=\left|b_{n}\right| \neq 0$, we have $\left|y_{j}\right|>0$ for all $1 \leqslant j \leqslant n$. Also, we have

$$
\begin{aligned}
\left|b_{j}-a_{j} c_{j-1} \frac{z_{j-2}}{z_{j-1}}-a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}\right| & \geqslant\left|b_{j}\right|-\left|a_{j} c_{j-1} \frac{z_{j-2}}{z_{j-1}}\right|-\left|a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}\right| \\
& \geqslant\left|b_{j}\right|-\left|a_{j}\right|-\left|c_{j}\right|>0 .
\end{aligned}
$$

Thus the theorem holds.

In general, we have the following theorem.

Theorem 2.5. If the tridiagonal matrix $A$ satisfies any one of the conditions below, then theorem 2.1 will not break down.
(i) $a_{i} \neq 0(i=2 \sim n), c_{j} \neq 0(j=1 \sim n-1)$ and $\left|b_{i}\right| \geqslant\left|a_{i}\right|+\left|c_{i}\right|(i=1 \sim n)$, and there exists at least one $j(1 \leqslant j \leqslant n)$ such that $\left|b_{j}\right|>\left|a_{j}\right|+\left|c_{j}\right|$.
(ii) $b_{i}>0(i=1 \sim n)$ or $b_{i}<0(i=1 \sim n)$, and $a_{i+1} c_{i} \leqslant 0(i=1 \sim n-1)$.
(iii) $b_{i} \geqslant 0(i=1 \sim n)$ or $b_{i} \leqslant 0(i=1 \sim n)$ with $b_{1}, b_{n} \neq 0$, and $a_{i+1} c_{i}<0$ ( $i=1 \sim n-1$ ).

Proof. These can be proved by induction, in a manner similar to theorem 2.4.

Theorem 2.6. If $A$ is strictly diagonally dominant, then the sequence $\phi_{i, j}$ is a strictly increasing function of $i$ for $i<j$, and a strictly decreasing function of $i$ for $i>j$.

Proof. This conclusion can be drawn easily from theorem 2.4 and lemma 2.1.

## 3. An example

As a simple example, we consider a general Toeplitz tridiagonal matrix $T$,

$$
T=\left[\begin{array}{ccccccc}
1 & -u & & & & &  \tag{10}\\
-l & 1 & -u & & & & \\
& \ddots & \ddots & \ddots & & & \\
& & -l & 1 & -u & & \\
& & & \ddots & \ddots & \ddots & \\
& & & & -l & 1 & -u \\
& & & & & -l & 1
\end{array}\right]
$$

For this matrix, we have the following theorem.
Theorem 3.1. The inverse of $T$ can be expressed in the following explicit way:

$$
\begin{array}{ll}
\left(T^{-1}\right)_{i, j}=\frac{\left(\lambda_{+}^{i}-\lambda_{-}^{i}\right)\left(\lambda_{+}^{n-j+1}-\lambda_{-}^{n-j+1}\right)}{\left(\lambda_{+}-\lambda_{-}\right)\left(\lambda_{+}^{n+1}-\lambda_{-}^{n+1}\right)} u^{j-i} & i<j \\
\left(T^{-1}\right)_{i, j}=\frac{\left(\lambda_{+}^{j}-\lambda_{-}^{j}\right)\left(\lambda_{+}^{n-i+1}-\lambda_{-}^{n-i+1}\right)}{\left(\lambda_{+}-\lambda_{-}\right)\left(\lambda_{+}^{n+1}-\lambda_{-}^{n+1}\right)} l^{i-j} & i \geqslant j \tag{12}
\end{array}
$$

where

$$
\begin{equation*}
\lambda_{+}=\frac{1+\sqrt{1-4 l u}}{2} \quad \lambda_{-}=\frac{1-\sqrt{1-4 l u}}{2} . \tag{13}
\end{equation*}
$$

Proof. According to theorem 2.1, we have:

$$
\begin{equation*}
z_{0}=1 \quad z_{1}=1 \quad z_{i}=z_{i-1}-l u z_{i-2} \quad i=2, \ldots, n \tag{14}
\end{equation*}
$$

and

$$
\begin{equation*}
y_{n+1}=1 \quad y_{n}=1 \quad y_{j}=y_{j+1}-l u y_{j+2} \quad j=n-1, \ldots, 1 \tag{15}
\end{equation*}
$$

It is obvious that

$$
y_{j}=z_{n+1-j} \quad j=1, \ldots, n
$$

It can be shown that $z_{i}$ can be expressed as

$$
\begin{equation*}
z_{i}=\beta_{0} \lambda_{+}^{i+1}+\beta_{1} \lambda_{-}^{i+1} \tag{16}
\end{equation*}
$$

where $\lambda_{+}$and $\lambda_{-}$are the roots of the quadratic equation $\lambda^{2}-\lambda+l u=0$.

$$
\lambda_{+}=\frac{1+\sqrt{1-4 l u}}{2} \quad \lambda_{-}=\frac{1-\sqrt{1-4 l u}}{2}
$$

From the initial conditions $z_{0}=z_{1}=1$, we have $\beta_{0}=-\beta_{1}$. Hence (16) becomes

$$
\begin{equation*}
z_{i}=\beta_{0}\left(\lambda_{+}^{i+1}-\lambda_{-}^{i+1}\right) \tag{17}
\end{equation*}
$$

Now, we have

$$
\begin{align*}
& \frac{z_{i-2}}{z_{i-1}}=\frac{\lambda_{+}^{i-1}-\lambda_{-}^{i-1}}{\lambda_{+}^{i}-\lambda_{-}^{i}}  \tag{18}\\
& \frac{y_{i+2}}{y_{i+1}}=\frac{z_{n-i-1}}{z_{n-i}}=\frac{\lambda_{+}^{n-i}-\lambda_{-}^{n-i}}{\lambda_{+}^{n-i+1}-\lambda_{-}^{n-i+1}} \tag{19}
\end{align*}
$$

Combine (18) and (19) with theorem 2.1, we have

$$
\begin{align*}
& \left(T^{-1}\right)_{i, i}=\frac{1}{1-l u\left(\frac{\lambda_{+}^{i-1}-\lambda_{-}^{i-1}}{\lambda_{+}^{i}-\lambda_{-}^{i}}+\frac{\lambda_{-}^{n-i}-\lambda_{-}^{n-i}}{\lambda_{+}^{n-i+1}-\lambda_{-}^{n-i+1}}\right)} \\
& =\frac{1}{1-\lambda_{+} \lambda_{-}\left(\frac{\lambda_{+}^{n}-\lambda_{+}^{n-i+1} \lambda_{-}^{i-1}-\lambda_{+}^{i-1} \lambda_{-}^{n-i+1}+\lambda_{-}^{n}+\lambda_{+}^{n}-\lambda_{+}^{i} \lambda_{-}^{n-i}-\lambda_{+}^{n-i} \lambda_{-}^{i}+\lambda_{-}^{n}}{\lambda_{+}^{n+1}-\lambda_{+}^{i} \lambda_{-}^{n-i+1}-\lambda_{-}^{i} \lambda_{+}^{n-i+1}+\lambda_{-}^{n+1}}\right)} \\
& =\frac{1}{1-\lambda_{+} \lambda_{-}\left(\frac{\left.2 \lambda_{+}^{n}-\lambda_{+}^{n-i} i_{-}^{i-1}\left(\lambda_{+}+\lambda_{-}\right)-\lambda_{+}^{i-1} \lambda_{-}^{n-i} \lambda_{-}+\lambda_{+}\right)+2 \lambda_{-}^{n}}{\lambda_{+}^{n+1}-\lambda_{+}^{i} \lambda_{-}^{-i+1}-\lambda_{-}^{i} \lambda_{+}^{n-i+1}+\lambda_{-}^{n+1}}\right)} \\
& =\frac{1}{1-\lambda_{+} \lambda_{-}\left(\frac{2 \lambda_{+}^{n}-\lambda_{+}^{n-i} \lambda_{-}^{i-1}-\lambda_{+}^{i-1} \lambda_{-}^{n-i}+2 \lambda_{-}^{n}}{\left.\lambda_{+}^{n+1}-\lambda_{+}^{i} \lambda_{-}^{n-i+1}-\lambda_{-}^{i_{-}^{n-i+1}+\lambda_{-}^{n+1}}\right)}\right.} \\
& =\frac{\left(\lambda_{+}^{i}-\lambda_{-}^{i}\right)\left(\lambda_{+}^{n-i+1}-\lambda_{-}^{n-i+1}\right)}{\lambda_{+}^{n+1}-\lambda_{+}^{i} \lambda_{-}^{n-i+1}-\lambda_{-}^{i} \lambda_{+}^{n-i+1}+\lambda_{-}^{n+1}-2 \lambda_{+}^{n+1} \lambda_{-}+\lambda_{+}^{n-i+1} \lambda_{-}^{i}+\lambda_{+}^{i} \lambda_{-}^{n-i+1}-2 \lambda_{+} \lambda_{-}^{n+1}} \\
& =\frac{\left(\lambda_{+}^{i}-\lambda_{-}^{i}\right)\left(\lambda_{+}^{n-i+1}-\lambda_{-}^{n-i+1}\right)}{\left(\lambda_{+}-\lambda_{-}\right)\left(\lambda_{+}^{n+1}-\lambda_{-}^{n+1}\right)} \tag{20}
\end{align*}
$$

From (20) and corollary 2.1, it is obvious that equations (11) and (12) hold.

### 3.1. Discussion

Based on theorem 3.1, we now discuss three cases.
Case 1. lu $=\frac{1}{4}$.
If $l u=\frac{1}{4}$, from (13) we have $\lambda_{+}=\lambda_{-}=\lambda=\frac{1}{2}$. For any $i>0$ we have

$$
\begin{equation*}
\lambda_{+}^{i}-\lambda_{-}^{i}=\left(\lambda_{+}-\lambda_{-}\right) \sum_{k=0}^{i-1}\left(\lambda_{+}^{k} \lambda_{-}^{i-1-k}\right)=\left(\lambda_{+}-\lambda_{-}\right) i \lambda^{i-1} \tag{21}
\end{equation*}
$$

Substituting (21) into (11) and (12), we have

$$
\begin{array}{ll}
\left(T^{-1}\right)_{i, j}=\frac{i(n-j+1)}{2(n+1)}\left(\frac{u}{l}\right)^{(j-i) / 2} & i<j \\
\left(T^{-1}\right)_{i, j}=\frac{j(n-i+1)}{2(n+1)}\left(\frac{l}{u}\right)^{(i-j) / 2} & i \geqslant j \tag{23}
\end{array}
$$

Case 2. $l u<\frac{1}{4}$.
If $l u<\frac{1}{4}$, then $1-4 l u>0, \lambda_{+}$and $\lambda_{-}$are both real numbers. If we set

$$
\begin{align*}
& \lambda_{+}=\frac{1+\sqrt{1-4 l u}}{2}=\gamma \mathrm{e}^{\theta}  \tag{24}\\
& \lambda_{-}=\frac{1-\sqrt{1-4 l u}}{2}=\gamma \mathrm{e}^{-\theta} \tag{25}
\end{align*}
$$

then from (24) and (25) we have

$$
2 \gamma \cosh \theta=1
$$

and

$$
\gamma^{2}=\frac{1+\sqrt{1-4 l u}}{2} \frac{1-\sqrt{1-4 l u}}{2}=l u .
$$

Hence

$$
\begin{equation*}
2 \sqrt{l u} \cosh \theta=1 \tag{26}
\end{equation*}
$$

For any $i>0$ we have

$$
\begin{equation*}
\lambda_{+}^{i}-\lambda_{-}^{i}=\gamma^{i} \mathrm{e}^{i \theta}-\gamma^{i} \mathrm{e}^{-i \theta}=2 \gamma^{i} \sinh i \theta=2(l u)^{i / 2} \sinh i \theta \tag{27}
\end{equation*}
$$

Substituting (27) into (11) and (12), we have

$$
\begin{array}{ll}
\left(T^{-1}\right)_{i, j}=\frac{\sinh i \theta \sinh (n-j+1) \theta}{\sinh \theta \sinh (n+1) \theta}\left(\frac{u}{l}\right)^{(j-i) / 2} & i<j \\
\left(T^{-1}\right)_{i, j}=\frac{\sinh j \theta \sinh (n-i+1) \theta}{\sinh \theta \sinh (n+1) \theta}\left(\frac{l}{u}\right)^{(i-j) / 2} & i \geqslant j \tag{29}
\end{array}
$$

where $\theta$ is defined in (26).
Case 3. $l u>\frac{1}{4}$.
If $l u>\frac{1}{4}$, then $1-4 l u<0, \lambda_{+}$and $\lambda_{-}$are both complex numbers. If we set

$$
\begin{align*}
& \lambda_{+}=\frac{1}{2}+\frac{\sqrt{4 l u-1}}{2} \mathrm{i}=\gamma \mathrm{e}^{\mathrm{i} \theta}  \tag{30}\\
& \lambda_{-}=\frac{1}{2}+\frac{\sqrt{4 l u-1}}{2} \mathrm{i}=\gamma \mathrm{e}^{-\mathrm{i} \theta} \tag{31}
\end{align*}
$$

where $i=\sqrt{-1}$. From (30) and (31) we have

$$
2 \gamma \cos \theta=1
$$

and

$$
\gamma^{2}=\left(\frac{1}{2}+\frac{\sqrt{4 l u-1}}{2} \mathrm{i}\right)\left(\frac{1}{2}+\frac{\sqrt{4 l u-1}}{2} \mathrm{i}\right)=l u .
$$

Hence

$$
\begin{equation*}
2 \sqrt{l u} \cos \theta=1 \tag{32}
\end{equation*}
$$

For any $i>0$ we have

$$
\begin{equation*}
\lambda_{+}^{i}-\lambda_{-}^{i}=\gamma^{i} \mathrm{e}^{i \theta}-\gamma^{i} \mathrm{e}^{-i \theta}=2 \gamma^{i} \sin i \theta=2(l u)^{i / 2} \sin i \theta \tag{33}
\end{equation*}
$$

Substituting (33) into (11) and (12), we have

$$
\begin{array}{ll}
\left(T^{-1}\right)_{i, j}=\frac{\sin i \theta \sin (n-j+1) \theta}{\sin \theta \sin (n+1) \theta}\left(\frac{u}{l}\right)^{(j-i) / 2} & i<j \\
\left(T^{-1}\right)_{i, j}=\frac{\sin j \theta \sin (n-i+1) \theta}{\sin \theta \sin (n+1) \theta}\left(\frac{l}{u}\right)^{(i-j) / 2} & i \geqslant j \tag{35}
\end{array}
$$

where $\theta$ is defined in (32).
This completes our discussion about general Toeplitz tridiagonal matrix inversion. It is straightforward to show that the result in [1] is a special case of our formula.

## 4. Block case

We now extend our algorithm to the block tridiagonal case where

$$
\mathbf{A}=\left[\begin{array}{ccccccc}
B_{1} & C_{1} & & & & & \\
A_{2} & B_{2} & C_{2} & & & & \\
& \ddots & \ddots & \ddots & & & \\
& & A_{j} & B_{j} & C_{j} & & \\
& & & \ddots & \ddots & \ddots & \\
& & & & A_{n-1} & B_{n-1} & C_{n-1} \\
& & & & & A_{n} & B_{n}
\end{array}\right]
$$

and $A_{j}, B_{j}$ and $C_{j}$ are $m \times m$ matrices.
Theorem 4.1. Define the second-order block recurrences

$$
\begin{equation*}
C_{i} Z_{i}=B_{i} Z_{i-1}-A_{i} Z_{i-2} \quad i=2,3, \ldots, n \tag{36}
\end{equation*}
$$

where $Z_{0}=I, Z_{1}=C_{1}^{-1} B_{1}$ and

$$
\begin{equation*}
A_{j} Y_{j}=B_{j} Y_{j+1}-C_{j} Y_{j+2} \quad j=n-1, n-2, \ldots, 1 \tag{37}
\end{equation*}
$$

where $Y_{n+1}=I, Y_{n}=A_{n}^{-1} B_{n}$. The inverse matrix $\mathbf{A}^{-1}=\left\{\Phi_{i, j}\right\}(1 \leqslant i, j \leqslant n)$ can be expressed as

$$
\begin{equation*}
\Phi_{j, j}=\left(B_{j}-A_{j} Z_{j-2} Z_{j-1}^{-1}-C_{j} Y_{j+2} Y_{j+1}^{-1}\right)^{-1} \tag{38}
\end{equation*}
$$

where $j=1,2, \ldots, n, A_{1}=0, C_{n}=0$ and

$$
\Phi_{i, j}= \begin{cases}-Z_{i-1} Z_{i}^{-1} \Phi_{i+1, j} & i<j  \tag{39}\\ -Y_{i+1} Y_{i}^{-1} \Phi_{i-1, j} & i>j\end{cases}
$$

Proof. Consider the $j$ th block column of the inverse matrix $\mathbf{A}^{-1}$. We have

$$
\left[\begin{array}{ccccccc}
B_{1} & C_{1} & & & & &  \tag{40}\\
A_{2} & B_{2} & C_{2} & & & & \\
& \ddots & \ddots & \ddots & & & \\
& & A_{j} & B_{j} & C_{j} & & \\
& & & \ddots & \ddots & \ddots & \\
& & & & A_{n-1} & B_{n-1} & C_{n-1} \\
& & & & & A_{n} & B_{n}
\end{array}\right]\left[\begin{array}{c}
\Phi_{1, j} \\
\vdots \\
\Phi_{j-1, j} \\
\Phi_{j, j} \\
\Phi_{j+1, j} \\
\vdots \\
\Phi_{n, j}
\end{array}\right]=\left[\begin{array}{c}
0 \\
\vdots \\
0 \\
I \\
0 \\
\vdots \\
0
\end{array}\right] .
$$

For $i<j$, we use induction on $i$.
Basis step. When $i=1$, the first equation of (40) is

$$
B_{1} \Phi_{1, j}+C_{1} \Phi_{2, j}=0
$$

from which we have

$$
\Phi_{1, j}=-B_{1}^{-1} C_{1} \Phi_{2, j}=-Z_{0} Z_{1}^{-1} \Phi_{2, j} .
$$

Equation (39) holds.
Induction step. We assume equation (39) holds for all $i$ in the interval $0<i \leqslant k-1<$ $j-1$, then for $i=k-1$, we have

$$
\begin{equation*}
\Phi_{k-1, j}=-Z_{k-2} Z_{k-1}^{-1} \Phi_{k, j} \tag{41}
\end{equation*}
$$

Also, from the $k$ th equation of (40), we have

$$
A_{k} \Phi_{k-1, j}+B_{k} \Phi_{k, j}+C_{k} \Phi_{k+1, j}=0
$$

Substituting the $\Phi_{k-1, j}$ in the above equation using (41), we have

$$
A_{k}\left(-Z_{k-2} Z_{k-1}^{-1}\right) \Phi_{k, j}+B_{k} \Phi_{k, j}+C_{k} \Phi_{k+1, j}=0
$$

or

$$
\begin{equation*}
\Phi_{k, j}=-\left(B_{k}-A_{k} Z_{k-2} Z_{k-1}^{-1}\right)^{-1} C_{k} \Phi_{k+1, j} \tag{42}
\end{equation*}
$$

From equation (36) we have

$$
\begin{aligned}
C_{k} & =B_{k} Z_{k-1} Z_{k}^{-1}-A_{k} Z_{k-2} Z_{k}^{-1} \\
& =B_{k} Z_{k-1} Z_{k}^{-1}-A_{k} Z_{k-2} Z_{k-1} Z_{k-1}^{-1} Z_{k}^{-1} \\
& =\left(B_{k}-A_{k} Z_{k-2} Z_{k-1}^{-1}\right) Z_{k-1} Z_{k}^{-1}
\end{aligned}
$$

Thus equation (42) becomes

$$
\Phi_{k, j}=-Z_{k-1} Z_{k}^{-1} \Phi_{k+1, j}
$$

Hence equation (39) holds when $i<j$. Similarly, we can show that when $i>j$, equation (39) also holds.

Now, the only thing left is to determine $\Phi_{j, j}$. From the $j$ th equation of (40), we have

$$
\begin{equation*}
A_{j} \Phi_{j-1, j}+B_{j} \Phi_{j, j}+C_{j} \Phi_{j+1, j}=1 \tag{43}
\end{equation*}
$$

From equation (39) we have

$$
\left\{\begin{array}{l}
\Phi_{j-1, j}=-Z_{j-2} Z_{j-1}^{-1} \Phi_{j, j}  \tag{44}\\
\Phi_{j+1, j}=-Y_{j+2} Y_{j+1}^{-1} \Phi_{j, j}
\end{array}\right.
$$

Substituting equation (44) into (43), we obtain

$$
A_{j}\left(-Z_{j-2} Z_{j-1}^{-1} \Phi_{j, j}\right)+B_{j} \Phi_{j, j}+C_{j}\left(-Y_{j+2} Y_{j+1}^{-1} \Phi_{j, j}\right)=1
$$

which is

$$
\left(B_{j}-A_{j} Z_{j-2} Z_{j-1}^{-1}-C_{j} Y_{j+2} Y_{j+1}^{-1}\right) \Phi_{j, j}=I .
$$

Thus equation (38) holds.
Corollary 4.1. The inverse matrix $\mathbf{A}^{-1}=\left\{\Phi_{i, j}\right\}$ can be expressed as

$$
\Phi_{j, j}=\left(B_{j}-A_{j} Z_{j-2} Z_{j-1}^{-1}-C_{j} Y_{j+2} Y_{j+1}^{-1}\right)^{-1}
$$

where $j=1,2, \ldots, n, A_{1}=0, C_{n}=0$ and

$$
\Phi_{i, j}= \begin{cases}(-1)^{j-i} Z_{i-1} Z_{j-1}^{-1} \Phi_{j, j} & i<j  \tag{45}\\ (-1)^{i-j} Y_{i+1} Y_{j+1}^{-1} \Phi_{j, j} & i>j\end{cases}
$$

## 5. An example (block Toeplitz case)

As a straightforward extension of theorem 4.1, we now consider the inversion of a block matrix

$$
\mathbf{T}=\left[\begin{array}{ccccccc}
B & C & & & & & \\
A & B & C & & & & \\
& \ddots & \ddots & \ddots & & & \\
& & A & B & C & & \\
& & & \ddots & \ddots & \ddots & \\
& & & & A & B & C \\
& & & & & A & B
\end{array}\right]
$$

where $A, B$ and $C$ are $m \times m$ matrices.
Let $\Lambda_{1}$ and $\Lambda_{2}$ be $m \times m$ matrices such that

$$
\left\{\begin{array}{l}
\Lambda_{1}+\Lambda_{2}=C^{-1} B  \tag{46}\\
\Lambda_{1} \Lambda_{2}=C^{-1} A
\end{array}\right.
$$

Let $\Delta_{1}$ and $\Delta_{2}$ be $m \times m$ matrices such that

$$
\left\{\begin{array}{l}
\Delta_{1}+\Delta_{2}=A^{-1} B  \tag{47}\\
\Delta_{1} \Delta_{2}=A^{-1} C
\end{array}\right.
$$

Define sequences $Z_{i}$ and $Y_{i}(i=0, \ldots, n)$ to be

$$
\begin{equation*}
Z_{i}=\sum_{k=0}^{i}\left(\Lambda_{2}^{i-k} \Lambda_{1}^{k}\right) \tag{48}
\end{equation*}
$$

and

$$
\begin{equation*}
Y_{i}=\sum_{k=0}^{n+1-i}\left(\Delta_{2}^{n+1-i-k} \Delta_{1}^{k}\right) \tag{49}
\end{equation*}
$$

then we have the following result.
Theorem 5.1. The inverse of matrix $\mathbf{T}$ can be expressed in the following explicit way:

$$
\begin{equation*}
\left(\mathbf{T}^{-1}\right)_{j, j}=\left(B-A Z_{j-2} Z_{j-1}^{-1}-C Y_{j+2} Y_{j+1}^{-1}\right)^{-1} \tag{50}
\end{equation*}
$$

where $j=1,2, \ldots, n$ and

$$
\left(\mathbf{T}^{-1}\right)_{i, j}= \begin{cases}(-1)^{j-i} Z_{i-1} Z_{j-1}^{-1}\left(T^{-1}\right)_{j, j} & i<j  \tag{51}\\ (-1)^{i-j} Y_{i+1} Y_{j+1}^{-1}\left(T^{-1}\right)_{j, j} & i>j\end{cases}
$$

Proof. To prove the theorem, we only need to show the sequences $Z_{i}$ and $Y_{i}$ defined in (48) and (49) satisfy the second-order block linear recurrences

$$
\begin{equation*}
C Z_{i}=B Z_{i-1}-A Z_{i-2} \quad i=2,3, \ldots, n \tag{52}
\end{equation*}
$$

where $Z_{0}=I, Z_{1}=C^{-1} B$ and

$$
\begin{equation*}
A Y_{j}=B Y_{j+1}-C Y_{j+2} \quad j=n-1, n-2, \ldots, 1 \tag{53}
\end{equation*}
$$

where $Y_{n+1}=I, Y_{n}=A^{-1} B$.
From (46) and (52), we have

$$
\begin{equation*}
Z_{i}=\left(\Lambda_{1}+\Lambda_{2}\right) Z_{i-1}-\Lambda_{1} \Lambda_{2} Z_{i-2} \tag{54}
\end{equation*}
$$

from which we have

$$
\begin{aligned}
Z_{i}-\Lambda_{2} Z_{i-1} & =\Lambda_{1}\left(Z_{i-1}-\Lambda_{2} Z_{i-2}\right)=\Lambda_{1}^{2}\left(Z_{i-2}-\Lambda_{2} Z_{i-3}\right) \\
& =\cdots=\Lambda_{1}^{i-1}\left(Z_{1}-\Lambda_{2} Z_{0}\right)=\Lambda_{1}^{i}
\end{aligned}
$$

Thus

$$
\begin{aligned}
& Z_{i}=\Lambda_{2} Z_{i-1}+\Lambda_{1}^{i} \quad i=1, \ldots, n \\
& Z_{i}=\Lambda_{2}^{i}+\Lambda_{2}^{i-1} \Lambda_{1}+\cdots+\Lambda_{2} \Lambda_{1}^{i-1}+\Lambda_{1}^{i}=\sum_{k=0}^{i} \Lambda_{2}^{i-k} \Lambda_{1}^{k}
\end{aligned}
$$

Similarly, we have

$$
Y_{i}=\Delta_{2}^{n+1-i}+\Delta_{2}^{n-i} \Lambda_{1}+\cdots+\Delta_{2} \Delta_{1}^{n-i}+\Lambda_{1}^{n+1-i}=\sum_{k=0}^{n+1-i} \Delta_{2}^{n+1-i-k} \Delta_{1}^{k}
$$

Now we make some discussions about the matrix. When $A=\varepsilon C$, where $\varepsilon$ is a constant factor, we have the following results.

Theorem 5.2. If $A=\varepsilon C$, the inverse of the matrix $\mathbf{T}$ can be determined by the following explicit formulae.

$$
\begin{align*}
& \left(\mathbf{T}^{-1}\right)_{i, j}=(-1)^{i-j}\left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-i}-\Psi_{2}^{n+1-i}\right)\left(\Psi_{1}-\Psi_{2}\right)^{-1}\left(\Psi_{1}^{n+1}-\Psi_{2}^{n+1}\right)^{-1} C^{-1} \\
& \quad i<j  \tag{55}\\
& \left(\mathbf{T}^{-1}\right)_{i, j}=(-\varepsilon)^{i-j}\left(\Psi_{1}^{i}-\Psi_{2}^{i}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\left(\Psi_{1}-\Psi_{2}\right)^{-1}\left(\Psi_{1}^{n+1}-\Psi_{2}^{n+1}\right)^{-1} C^{-1} \\
& \quad i \geqslant j \tag{56}
\end{align*}
$$

where $\Psi_{1}$ and $\Psi_{2}$ are $m \times m$ matrices that satisfy

$$
\left\{\begin{array}{l}
\Psi_{1}+\Psi_{2}=C^{-1} B  \tag{57}\\
\Psi_{1} \Psi_{2}=\varepsilon I
\end{array}\right.
$$

Proof. Since $A=\varepsilon C$, from (46) and (47) we have $\Lambda_{1} \Lambda_{2}=\varepsilon I$. Thus $\Lambda_{1}$ and $\Lambda_{2}$ commute. Similarly $\Delta_{1}$ and $\Delta_{2}$ commute. Also we have $\Lambda_{1}+\Lambda_{2}=\varepsilon\left(\Delta_{1}+\Delta_{2}\right)=C^{-1} B$, and $\Lambda_{1} \Lambda_{2}=\varepsilon^{2} \Delta_{1} \Delta_{2}$, hence

$$
\Lambda_{1}=\varepsilon \Delta_{1}=\Psi_{1} \quad \Lambda_{2}=\varepsilon \Delta_{2}=\Psi_{2}
$$

Equation (48) now becomes

$$
\begin{equation*}
Z_{i}=\sum_{k=0}^{i} \Lambda_{1}^{i-k} \Lambda_{2}^{k}=\left(\Psi_{1}^{i+1}-\Psi_{2}^{i+1}\right)\left(\Psi_{1}-\Psi_{2}\right)^{-1} \tag{58}
\end{equation*}
$$

and (49) becomes

$$
\begin{equation*}
Y_{i}=\sum_{k=0}^{n+1-i} \Delta_{1}^{n+1-i-k} \Delta_{1}^{k}=\varepsilon^{i-n-1}\left(\Psi_{1}^{n+2-i}-\Psi_{2}^{n+2-i}\right)\left(\Psi_{1}-\Psi_{2}\right)^{-1} \tag{59}
\end{equation*}
$$

Substituting (58) and (59) into (50), we have

$$
\begin{align*}
\left(\mathbf{T}^{-1}\right)_{j, j}= & \left(B-A Z_{j-2} Z_{j-1}^{-1}-C Y_{j+2} Y_{j+1}^{-1}\right)^{-1} \\
= & {\left[B-A\left(\Psi_{1}^{j-1}-\Psi_{2}^{j-1}\right)\left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)^{-1}\right.} \\
& \left.+\varepsilon C\left(\Psi_{1}^{n-j}-\Psi_{2}^{n-j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)^{-1}\right]^{-1} \\
= & \left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\left[B\left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\right. \\
& \left.+A\left(\Psi_{1}^{j-1}-\Psi_{2}^{j-1}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)+A\left(\Psi_{1}^{n-j}-\Psi_{2}^{n-j}\right)\left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\right]^{-1} \\
= & \left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\left[B\left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\right. \\
& \left.+A\left(2 \Psi_{1}^{n}+2 \Psi_{2}^{n}-\left(\Psi_{1}+\Psi_{2}\right)\left(\Psi_{1}^{n-j} \Psi_{2}^{j-1}+\Psi_{2}^{n-j} \Psi_{1}^{j-1}\right)\right)\right]^{-1} \\
= & \left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\left[B\left(\Psi_{1}^{n+1}+\Psi_{2}^{n+1}\right)-A\left(2 \Psi_{1}^{n}+2 \Psi_{2}^{n}\right)\right]^{-1} \\
= & \left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right) \\
& \times\left[C\left(\Psi_{1}+\Psi_{2}\right)\left(\Psi_{1}^{n+1}+\Psi_{2}^{n+1}\right)-\varepsilon C\left(2 \Psi_{1}^{n}+2 \Psi_{2}^{n}\right)\right]^{-1} \\
= & \left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right) \\
& \times\left[\Psi_{1}^{n+2}+\Psi_{2}^{n+2}-\left(2 \varepsilon \Psi_{1}^{n}-\Psi_{2} \Psi_{1}^{n+1}\right)-\left(2 \varepsilon \Psi_{2}^{n}-\Psi_{1} \Psi_{2}^{n+1}\right)\right]^{-1} C^{-1} \\
= & \left(\Psi_{1}^{j}-\Psi_{2}^{j}\right)\left(\Psi_{1}^{n+1-j}-\Psi_{2}^{n+1-j}\right)\left(\Psi_{1}-\Psi_{2}\right)^{-1}\left(\Psi_{1}^{n+1}-\Psi_{2}^{n+1}\right)^{-1} C^{-1} \tag{60}
\end{align*}
$$

Using (58), (59) and theorem 5.1, we can obtain equation (51).

### 5.1. Discussion

Based on theorem 5.2, we now discuss two special cases.
Case 1. $\varepsilon=0$.
When $\varepsilon=0, A=\varepsilon C=0$. (57) becomes

$$
\left\{\begin{array}{l}
\Psi_{1}+\Psi_{2}=C^{-1} B  \tag{61}\\
\Psi_{1} \Psi_{2}=0
\end{array}\right.
$$

which has solutions $\Psi_{1}=C^{-1} B, \Psi_{2}=0$. Hence from theorem 5.2 we have

$$
\begin{align*}
\left(\mathbf{T}^{-1}\right)_{i, j} & =(-1)^{i-j} \Psi_{1}^{j} \Psi_{1}^{n+1-i} \Psi_{1}^{-1} \Psi_{1}^{-(n+1)} C^{-1} \\
& =(-1)^{i-j}\left(C^{-1} B\right)^{j-i} B^{-1} \quad i \leqslant j  \tag{62}\\
\left(\mathbf{T}^{-1}\right)_{i, j} & =0 \quad i>j \tag{63}
\end{align*}
$$

Case 2. $A=C=0$.
When $A=C=0$. the inverse matrix is extremely simple,

$$
\begin{array}{lr}
\left(\mathbf{T}^{-1}\right)_{i, j}=B^{-1} & i=j \\
\left(\mathbf{T}^{-1}\right)_{i, j}=0 & i \neq j . \tag{65}
\end{array}
$$

### 5.2. Solution of equation (57)

We now find the explicit solution of equation (57) in theorem 5.2. For simplicity, suppose $C^{-1} B$ is nondefective. Let $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{m}$ be the eigenvalues of $C^{-1} B$ and $Q$ be the matrix of the eigenvectors such that

$$
\begin{equation*}
C^{-1} B=Q \operatorname{diag}_{m}\left(\lambda_{k}\right) Q^{-1} \tag{66}
\end{equation*}
$$

where $\operatorname{diag}_{m}\left(\lambda_{k}\right)$ is defined to be an $m \times m$ diagonal matrix with $\lambda_{k}(k=1 \ldots m)$ being the diagonal element. Set the solution of (57) to be

$$
\begin{align*}
& \Psi_{1}=Q \operatorname{diag}\left(\lambda_{k}^{+}\right) Q^{-1}  \tag{67}\\
& \Psi_{2}=Q \operatorname{diag}\left(\lambda_{k}^{-}\right) Q^{-1} \tag{68}
\end{align*}
$$

then we have

$$
\left\{\begin{array}{l}
\lambda_{k}^{+}+\lambda_{k}^{-}=\lambda_{k}  \tag{69}\\
\lambda_{k}^{+} \lambda_{k}^{-}=\varepsilon
\end{array}\right.
$$

or in other words, $\lambda_{k}^{+}$and $\lambda_{k}^{-}$are the roots of $r^{2}-\lambda_{k} r+\varepsilon=0$. Using the same analysis as in section 3 , we have the following results.

When $\lambda_{k}^{2}>4 \varepsilon$, we have

$$
\begin{equation*}
\left(\lambda_{k}^{+}\right)^{i}-\left(\lambda_{k}^{-}\right)^{i}=2 \varepsilon^{i / 2} \sinh i \theta_{k} \quad \text { where } 2 \varepsilon^{1 / 2} \cosh \theta_{k}=\lambda_{k} \tag{70}
\end{equation*}
$$

When $\lambda_{k}^{2} \leqslant 4 \varepsilon$, we have

$$
\begin{equation*}
\left(\lambda_{k}^{+}\right)^{i}-\left(\lambda_{k}^{-}\right)^{i}=2 \varepsilon^{i / 2} \sin i \theta_{k} \quad \text { where } 2 \varepsilon^{1 / 2} \cos \theta_{k}=\lambda_{k} \tag{71}
\end{equation*}
$$

Theorem 5.3. If $A=\varepsilon C$, the inverse of the matrix $\mathbf{T}$ can be determined by the following explicit formulae.

$$
\left(\mathbf{T}^{-1}\right)_{i, j}=(-1)^{j-i} \varepsilon^{(j-i-1) / 2} Q \operatorname{diag}_{m}\left\{\frac{\sinh \left(j \theta_{k}\right) \sinh (n+1-i) \theta_{k}}{\sinh \theta_{k} \sinh \left((n+1) \theta_{k}\right)}\right\} Q^{-1} C^{-1} \quad i<j
$$

$$
\begin{equation*}
\left(\mathbf{T}^{-1}\right)_{i, j}=(-1)^{i-j} \varepsilon^{(i-j-1) / 2} Q \operatorname{diag}_{m}\left\{\frac{\sinh \left(i \theta_{k}\right) \sinh (n+1-j) \theta_{k}}{\sinh \theta_{k} \sinh (n+1) \theta_{k}}\right\} Q^{-1} C^{-1} \quad i \geqslant j \tag{72}
\end{equation*}
$$

where $Q$ and $\theta_{k}$ satisfy

$$
\begin{equation*}
C^{-1} B=Q \operatorname{diag}_{m}\left\{\lambda_{k}\right\} Q^{-1} \quad \text { and } \quad 2 \varepsilon^{1 / 2} \cosh \theta_{k}=\lambda_{k} \tag{74}
\end{equation*}
$$

If $\lambda_{k}^{2} \leqslant 4 \varepsilon(1 \leqslant k \leqslant m)$, the hyperbolic sines and cosines in (72)-(74) become sines and cosines, respectively.

## Appendix A. Proof of theorem 2.1

Proof. Consider the $j$ th column of the inverse matrix $A^{-1}$, we have the equations

$$
\left[\begin{array}{ccccccc}
b_{1} & c_{1} & & & & &  \tag{A1}\\
a_{2} & b_{2} & c_{2} & & & & \\
& \ddots & \ddots & \ddots & & & \\
& & a_{j} & b_{j} & c_{j} & & \\
& & & \ddots & \ddots & \ddots & \\
& & & & a_{n-1} & b_{n-1} & c_{n-1} \\
& & & & & a_{n} & b_{n}
\end{array}\right]\left[\begin{array}{c}
\phi_{1, j} \\
\vdots \\
\phi_{j-1, j} \\
\phi_{j, j} \\
\phi_{j+1, j} \\
\vdots \\
\phi_{n, j}
\end{array}\right]=\left[\begin{array}{c}
0 \\
\vdots \\
0 \\
1 \\
0 \\
\vdots \\
0
\end{array}\right] .
$$

For $i<j$, we use induction on $i$.
Basis step. When $i=1$, the first equation of (A1) is

$$
b_{1} \phi_{1, j}+c_{1} \phi_{2, j}=0
$$

from which we have

$$
\phi_{1, j}=-\frac{c_{i} \phi_{2, j}}{b_{1}}=-c_{1} \frac{z_{0}}{z_{1}} \phi_{2, j}
$$

Equation (4) holds.
Induction step. We assume equation (4) holds for all $i$ in the interval $0<i \leqslant k-1<$ $j-1$, then for $i=k-1$, we have

$$
\phi_{k-1, j}=-c_{k-1} \frac{z_{k-2}}{z_{k-1}} \phi_{k, j} .
$$

Also, from the $k$ th equation of equations (A1), we have

$$
\begin{equation*}
a_{k} \phi_{k-1, j}+b_{k} \phi_{k, j}+c_{k} \phi_{k+1, j}=0 . \tag{A2}
\end{equation*}
$$

Substituting $\phi_{k-1, j}$ into equation (A2), we have

$$
a_{k}\left(-c_{k-1} \frac{z_{k-2}}{z_{k-1}}\right) \phi_{k, j}+b_{k} \phi_{k, j}+c_{k} \phi_{k+1, j}=0
$$

or

$$
\begin{equation*}
\phi_{k, j}=-c_{k} \frac{1}{b_{k}-a_{k} c_{k-1} \frac{z_{k-2}}{z_{k-1}}} \phi_{k+1, j} . \tag{A3}
\end{equation*}
$$

From equation (1), we have

$$
\frac{z_{k}}{z_{k-1}}=b_{k}-a_{k} c_{k-1} \frac{z_{k-2}}{z_{k-1}}
$$

thus equation (A3) becomes

$$
\phi_{k, j}=-c_{k} \frac{z_{k-1}}{z_{k}} \phi_{k+1, j}
$$

Hence equation (4) holds when $i<j$. Similarly, we can show that when $i>j$, equation (4) also holds.

Now, the only thing left is to determine $\phi_{j, j}$. From the $j$ th row of equation (A1), we have

$$
\begin{equation*}
a_{j} \phi_{j-1, j}+b_{j} \phi_{j, j}+c_{j} \phi_{j+1, j}=1 \tag{A4}
\end{equation*}
$$

From equation (4), we have

$$
\left\{\begin{array}{l}
\phi_{j-1, j}=-c_{j-1} \frac{z_{j-2}}{z_{j-1}} \phi_{j, j}  \tag{A5}\\
\phi_{j+1, j}=-a_{j+1} \frac{y_{j+2}}{y_{j+1}} \phi_{j, j}
\end{array}\right.
$$

Substituting equation (A5) into equation (A4), we have

$$
a_{j}\left(-c_{j-1} \frac{z_{j-2}}{z_{j-1}} \phi_{j, j}\right)+b_{j} \phi_{j, j}+c_{j}\left(-a_{j+1} \frac{y_{j+2}}{y_{j+1}} \phi_{j, j}\right)=1
$$

which gives

$$
\left(b_{j}-a_{j} c_{j-1} \frac{z_{j-2}}{z_{j-1}}-a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}\right) \phi_{j, j}=1 .
$$

Thus equation (3) holds.

## Appendix B. Proof of theorem 2.2

Proof. The idea is that since only $y_{i+1} / y_{i}$ and $z_{i-1} / z_{i}$ are required in theorem 2.1, we do not need to compute every $y_{j}(j=n-1, \ldots, 1)$ and $z_{i}(i=2, \ldots, n)$ explicitly. We denote

$$
\begin{equation*}
\frac{z_{i}}{z_{i-1}}=\zeta_{i} \tag{B1}
\end{equation*}
$$

Then equation (1) becomes

$$
\begin{equation*}
\zeta_{i}=b_{i}-a_{i} c_{i-1} / \zeta_{i-1} \quad \text { with } i=2, \ldots, n, \zeta_{1}=\frac{z_{1}}{z_{0}}=b_{1} \tag{B2}
\end{equation*}
$$

From (B1), (3) and (4) become

$$
\begin{equation*}
\phi_{j, j}=\frac{1}{\zeta_{j}-a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}} \tag{B3}
\end{equation*}
$$

where $j=1,2, \ldots, n, c_{n}=0$ and

$$
\phi_{i, j}= \begin{cases}-\frac{c_{i}}{\zeta_{i}} \phi_{i+1, j} & i<j  \tag{B4}\\ -a_{i} \frac{y_{i+1}}{y_{i}} \phi_{i-1, j} & i>j\end{cases}
$$

From (2), we have

$$
\begin{equation*}
a_{j+1} c_{j} \frac{y_{j+2}}{y_{j+1}}=b_{j}-\frac{y_{j}}{y_{j+1}} \tag{B5}
\end{equation*}
$$

where $j=n-1, n-2, \ldots, 1, y_{n+1}=1$ and $y_{n}=b_{n}$. If we define

$$
\begin{equation*}
\gamma_{j}=b_{j}-\frac{y_{j}}{y_{j+1}} \tag{B6}
\end{equation*}
$$

where $j=n-1, \ldots, 1$ and $\gamma_{n}=b_{n}-y_{n} / y_{n+1}=0$, then (B5) becomes

$$
\begin{equation*}
\gamma_{j}=\frac{a_{j+1} c_{j}}{b_{j+1}-\gamma_{j+1}} \quad j=n-1, \ldots, 1 \tag{B7}
\end{equation*}
$$

Hence, the inverse of the matrix $A$ can be expressed as

$$
\begin{equation*}
\phi_{j, j}=\frac{1}{\zeta_{j}-\gamma_{j}} \quad j=1,2, \ldots, n \tag{B8}
\end{equation*}
$$

and

$$
\phi_{i, j}= \begin{cases}-\frac{c_{i}}{\zeta_{i}} \phi_{i+1, j} & i<j  \tag{B9}\\ -\frac{a_{i}}{b_{i}-\gamma_{i}} \phi_{i-1, j} & i>j\end{cases}
$$

Now, the computation of $\left\{\phi_{i, j}\right\}$ can be carried out in the following steps.
(i) Compute $\zeta_{i}$ and $\frac{c_{i}}{\zeta_{i}}(i=1, \ldots, n)$ using equation (B2).
(ii) Compute $\gamma_{j}$ and $\frac{a_{j}}{b_{j}-\gamma_{j}}(j=n, \ldots, 1)$ using equation (B7).
(iii) Compute $\phi_{j, j}(j=1, \ldots, n)$ using equation (B8).
(iv) Compute $\phi_{i, j}(i \neq j)$ using equation (B9).

Computational cost. In step $1,3(n-1)$ floating point operations are required to calculate the values of $\zeta_{i}(i=1, \ldots, n)$. Note that during the computation of $\zeta_{i}$, we already have the values of $c_{i} / \zeta_{i}$, which will be used in step 4 . Similarly, $3(n-1)$ arithmetic operations are
required to obtain $\gamma_{j}$ and $a_{j} /\left(b_{j}-\gamma_{j}\right)(j=n, \ldots, 1)$. In step 3 , all $\phi_{j, j}(j=1, \ldots, n)$ can be obtained in $2 n-1$ operations. Note that one operation is saved by using $\gamma_{n}=0$. Since we have all the values of $c_{i} / \zeta_{i}$ and $a_{i} /\left(b_{i}-\gamma_{i}\right)(i=1 \sim n)$, step 4 can be completed with only $n^{2}-n$ floating point operations. Thus, the total cost of the method is $n^{2}+7 n-7$.

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